Open Problem: Object representations

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How should we represent objects in our scenes?

- A box?
- A mask / group of pixels?
- Keypoints?
- A 3D model?



A box?

- Advantages:
 - Low dimensional (4 values)
 - Easy to annotate
- Disadvantages:
 - Distracted by occlusions
 - Too large
 - Not enough information



A mask / group of pixels?

- Advantages:
 - More detailed
 - Handles occlusions
- Disadvantages:
 - Harder to annotate
 - Not much more information than box
 - Not enough information



Mask R-CNN, He et al., ICCV 2017 Bottom-up Object Detection by Grouping Extreme and Center Points, Zhou et al., CVPR 2019

Keypoints?

- Advantages:
 - Low dimensional
 - More information
- Disadvantages:
 - Class specific
 - Ill-defined for many classes
 - Harder to annotate



A 3D model?

- Advantages:
 - Very detailed
- Disadvantages:
 - Too large
 - Very hard to annotate
 - Infeasible for non-human
 - Not much more information



How do we represent stuff?

Ill-defined

